

Indian Institute of Science
E9–252: Mathematical Methods and Techniques in Signal Processing
Instructor: Shayan G. Srinivasa
Homework #6 Solutions, Fall 2017

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Late submission policy: Points scored = Correct points scored $\times e^{-d}$, $d = \#$ days late
Assigned date: Oct. 9th 2017 **Due date:** Oct. 23rd 2017 by end of the day

PROBLEM 1:

Problem 3.19 from P.P Vaidyanathan's Book

(9 points)

Solution: From the figure in the question, we obtain

$$G_m(z) = \frac{k_m^* + z^{-1}G_{m-1}(z)}{1 + k_m z^{-1}G_{m-1}(z)}$$

The poles of $G_m(z)$ are the zeros of $1 + k_m z^{-1}G_{m-1}(z)$. Thus,

$$\begin{aligned} 1 + k_m z^{-1}G_{m-1}(z) = 0 &\implies z^{-1} = -\frac{1}{k_m G_{m-1}(z)} \\ z = -k_m G_{m-1}(z) &\implies |z| = |k_m| |G_{m-1}(z)| = |k_m| < 1 \end{aligned}$$

Note that z is a variable in the above case. Thus, the poles of $G_m(z)$ are inside unit circle. As $|G_{m-1}(z)| = 1 \implies G_{m-1}(z) = e^{jf(z)}$.

$$|G_m(z)| = \left| \frac{k_m^* + z^{-1}G_{m-1}(z)}{1 + k_m z^{-1}G_{m-1}(z)} \right| = \frac{|k_m^* + z^{-1}G_{m-1}(z)|}{|1 + k_m z^{-1}G_{m-1}(z)|}$$

If $k_m = a + jb$,

$$\begin{aligned} |k_m^* + z^{-1}G_{m-1}(z)| &= |a - jb + \cos(f(z) - 1) + j\sin(f(z) - 1)| \\ &= (a^2 + \cos^2(f(z) - 1) + 2a\cos(f(z) - 1) + b^2 + \sin^2(f(z) - 1) - 2b\sin(f(z) - 1))^{1/2} \\ |1 + k_m z^{-1}G_{m-1}(z)| &= |1 + (a + jb)(\cos(f(z) - 1) + j\sin(f(z) - 1))| \\ &= (1 + a^2\cos^2(f(z) - 1) + b^2\sin^2(f(z) - 1) - 2b\sin(f(z) - 1) + 2a\cos(f(z) - 1) \\ &\quad - 2abc\cos(f(z) - 1)\sin(f(z) - 1) + b^2\cos^2(f(z) - 1) + a^2\sin^2(f(z) - 1) \\ &\quad + 2abc\cos(f(z) - 1)\sin(f(z) - 1))^{1/2} \\ &= (1 + a^2 + b^2 - 2b\sin(f(z) - 1) + 2a\cos(f(z) - 1))^{1/2} \\ &= |k_m^* + z^{-1}G_{m-1}(z)| \implies |G_m(z)| = 1 \end{aligned}$$

Part b) follows from induction using part a).

PROBLEM 2:

Problem 3.20 from P.P Vaidyanathan's Book

(10 points)

Solution: As $P_0(z)$ is hermitian, $\tilde{P}_0(z) = z^N P_0(z)$. As $P_1(z)$ is generalized hermitian, $\tilde{P}_1(z) = cz^N P_1(z)$, where $|c| = 1$. We prove the result by expressing $A_0(z)$, $A_1(z)$ and d in terms of c , $P_0(z)$, $P_1(z)$ and $D(z)$.

$$\begin{aligned} H_0(z) &= \frac{\beta A_0(z) + \beta^* A_1(z)}{2} \implies P_0(z) = \frac{\beta A_0(z) + \beta^* A_1(z)}{2} D(z) \\ H_1(z) &= d \frac{\beta A_0(z) - \beta^* A_1(z)}{2} \implies P_1(z) = d \frac{\beta A_0(z) - \beta^* A_1(z)}{2} D(z) \\ \implies A_0(z) &= \left(\frac{P_0(z)}{D(z)} + \frac{P_1(z)}{dD(z)} \right) \frac{1}{\beta} \text{ and } A_1(z) = \left(\frac{P_0(z)}{D(z)} - \frac{P_1(z)}{dD(z)} \right) \frac{1}{\beta^*} \end{aligned}$$

$$|H_0(z)|^2 + |H_1(z)|^2 = 1 \implies |P_0(z)|^2 + |P_1(z)|^2 = |D(z)|^2 \implies z^N P_0^2(z) + cz^N P_1^2(z) = |D(z)|^2.$$

$$\begin{aligned} |A_0^2(z)| &= \frac{1}{|D(z)|^2} \frac{z^N}{\beta\beta^*} \left(P_0(z) + \frac{P_1(z)}{d} \right) \left(P_0(z) + c \frac{P_1(z)}{d^*} \right) \\ &= \frac{z^N}{|D(z)|^2} \left(P_0^2(z) + \frac{cP_0(z)P_1(z)}{d^*} + cP_1^2(z) + \frac{P_0(z)P_1(z)}{d} \right) \\ &= \frac{1}{|D(z)|^2} \left(|D(z)|^2 + \left(\frac{c}{d^*} + \frac{1}{d} \right) P_0(z)P_1(z) \right) \\ &= 1 + \left(\frac{c}{d^*} + \frac{1}{d} \right) \frac{P_0(z)P_1(z)}{|D(z)|^2}. \\ |A_1^2(z)| &= \frac{1}{|D(z)|^2} \frac{z^N}{\beta\beta^*} \left(P_0(z) - \frac{P_1(z)}{d} \right) \left(P_0(z) - c \frac{P_1(z)}{d^*} \right) \\ &= \frac{z^N}{|D(z)|^2} \left(P_0^2(z) - \frac{cP_0(z)P_1(z)}{d^*} + cP_1^2(z) - \frac{P_0(z)P_1(z)}{d} \right) \\ &= 1 - \left(\frac{c}{d^*} + \frac{1}{d} \right) \frac{P_0(z)P_1(z)}{|D(z)|^2}. \end{aligned}$$

Let us choose $d : \left(\frac{c}{d^*} + \frac{1}{d} \right) = 0$, then, $|A_0^2(z)| = |A_1^2(z)| = 1$. We can choose such d as $\frac{c}{d^*} = \frac{1}{d} \implies |c| = 1$. Thus, we can obtain $A_0(z)$ and $A_1(z)$ as unit magnitude all pass filters with $|\beta| = |d| = 1$.

PROBLEM 3:

Problem 3.21 from P.P Vaidyanathan's Book

(6 points)

Solution: If $A_1(z) = cA_0(z)$, then $G(z) = (1+c)A_0(z) \implies |G(z)| = |1+c||A_0(z)| = |1+c|b$ where $|A_0(z)| = b$. Thus, $G(z)$ is all pass filter. If $G(z) = A_0(z) + A_1(z)$ is all pass filter, then, as $A_0(z)$ and $A_1(z)$ are all pass filters they can be represented by,

$$A_0(z) = be^{jf(z)} \text{ and } A_1(z) = ce^{jh(z)}$$

$G(z)$ is obtained as:

$$\begin{aligned} G(z) &= A_0(z) + A_1(z) = be^{jf(z)} + ce^{jh(z)} \\ &= b\cos f(z) + jbs\sin f(z) + c\cosh(z) + jc\sinh(z) \\ |G(z)|^2 &= b^2\cos^2 f(z) + c^2\cos^2 h(z) + 2bcc\cos f(z)\cosh(z) + b^2\sin^2 f(z) + c^2\sin^2 h(z) + 2bc\sin f(z)\sinh(z) \\ &= b^2 + c^2 + 2bcc(\cos(f(z) - h(z))) \end{aligned}$$

As b , c and $|G(z)|^2$ are constant, thus,

$$\begin{aligned} \cos(f(z) - h(z)) &= d \text{ (const)} \implies f(z) - h(z) = \cos^{-1}d = d' \implies h(z) = f(z) - d' \\ \implies A_1(z) &= ce^{jh(z)} = ce^{jf(z)-d'} = mA_0(z). \end{aligned}$$