

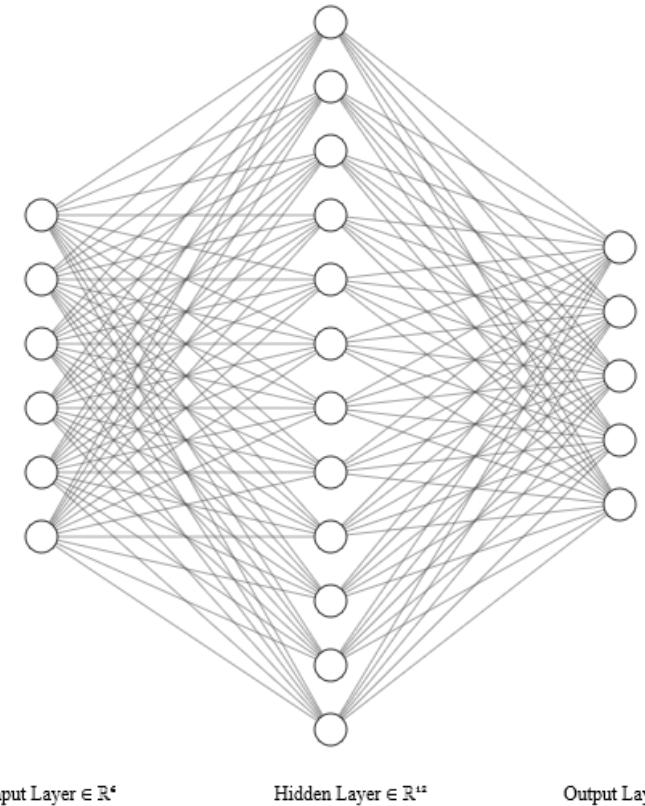
Back propagation for CNN

Prayag and Amrutha

In this lecture we will

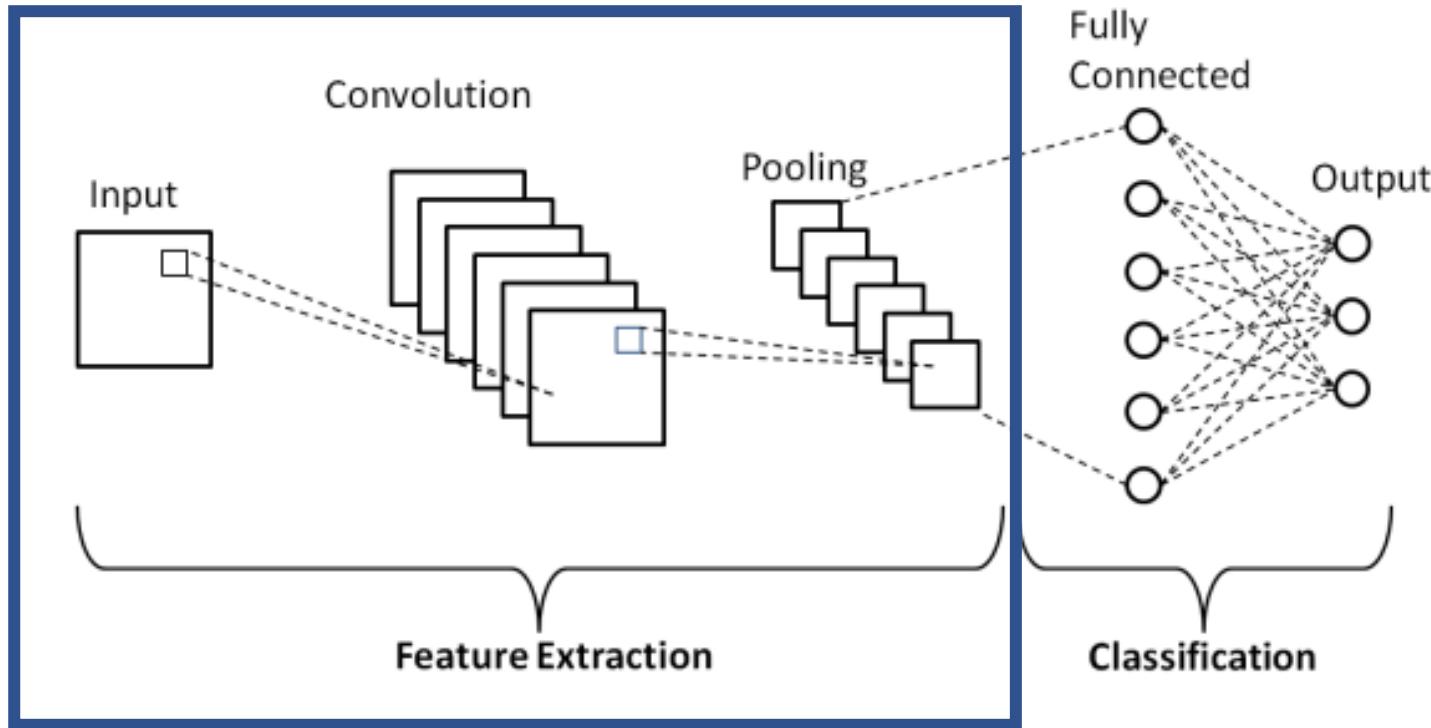
- Briefly revisit MLP
- Look at single block of CNN architecture
- Understand weight sharing concept
- Compute local gradients
- Derive update rule
- Summarize

Multi-layer perceptron



1. Forward pass: Compute the output without any updates.
2. Backward pass:
 - Compute the error $E(\text{output}, \text{desired signal})$
 - Compute the gradient
 - Update the weight parameters of the network

CNN architecture



- The block is repeated many times
 - Depending on the application
 - Depending on the computational resources available

CNN cont.

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

w_{11}	w_{12}
w_{21}	w_{22}

Rot(180)

w_{22}	w_{21}
w_{12}	w_{11}

x_{11}	$\textcolor{red}{w_{22}}$	x_{13}
x_{21}	x_{22}	$\textcolor{red}{w_{11}}$
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	$\textcolor{red}{w_{22}}$
x_{21}	$\textcolor{red}{w_{12}}$	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	$\textcolor{red}{w_{21}}$
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	$\textcolor{red}{w_{21}}$
x_{31}	$\textcolor{red}{w_{12}}$	$\textcolor{red}{w_{11}}$

CNN cont.

x_{11}	$\textcolor{red}{w_{22}}$	x_{12}
x_{21}	$\textcolor{red}{w_{11}}$	x_{22}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	$\textcolor{red}{w_{22}}$
x_{21}	x_{22}	$\textcolor{red}{w_{12}}$
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	$\textcolor{red}{w_{21}}$
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	$\textcolor{red}{w_{22}}$	x_{22}
x_{31}	$\textcolor{red}{w_{12}}$	x_{32}

$$h_{11} = x_{11}w_{22} + x_{12}w_{21} + x_{21}w_{12} + x_{22}w_{11}$$

$$h_{12} = x_{12}w_{22} + x_{13}w_{21} + x_{22}w_{12} + x_{23}w_{11}$$

$$h_{21} = x_{21}w_{22} + x_{22}w_{21} + x_{31}w_{12} + x_{32}w_{11}$$

$$h_{22} = x_{22}w_{22} + x_{23}w_{21} + x_{32}w_{12} + x_{33}w_{11}$$

Activation function and pooling

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

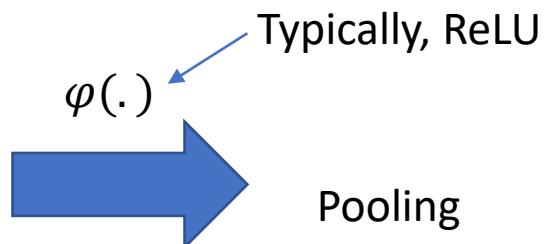
$$h_{11} = x_{11}w_{22} + x_{12}w_{21} + x_{21}w_{12} + x_{22}w_{11}$$

$$h_{12} = x_{12}w_{22} + x_{13}w_{21} + x_{22}w_{12} + x_{23}w_{11}$$

$$h_{21} = x_{21}w_{22} + x_{22}w_{21} + x_{31}w_{12} + x_{32}w_{11}$$

$$h_{22} = x_{22}w_{22} + x_{23}w_{21} + x_{32}w_{12} + x_{33}w_{11}$$

h_{11}	h_{12}
h_{21}	h_{22}



Weight sharing

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

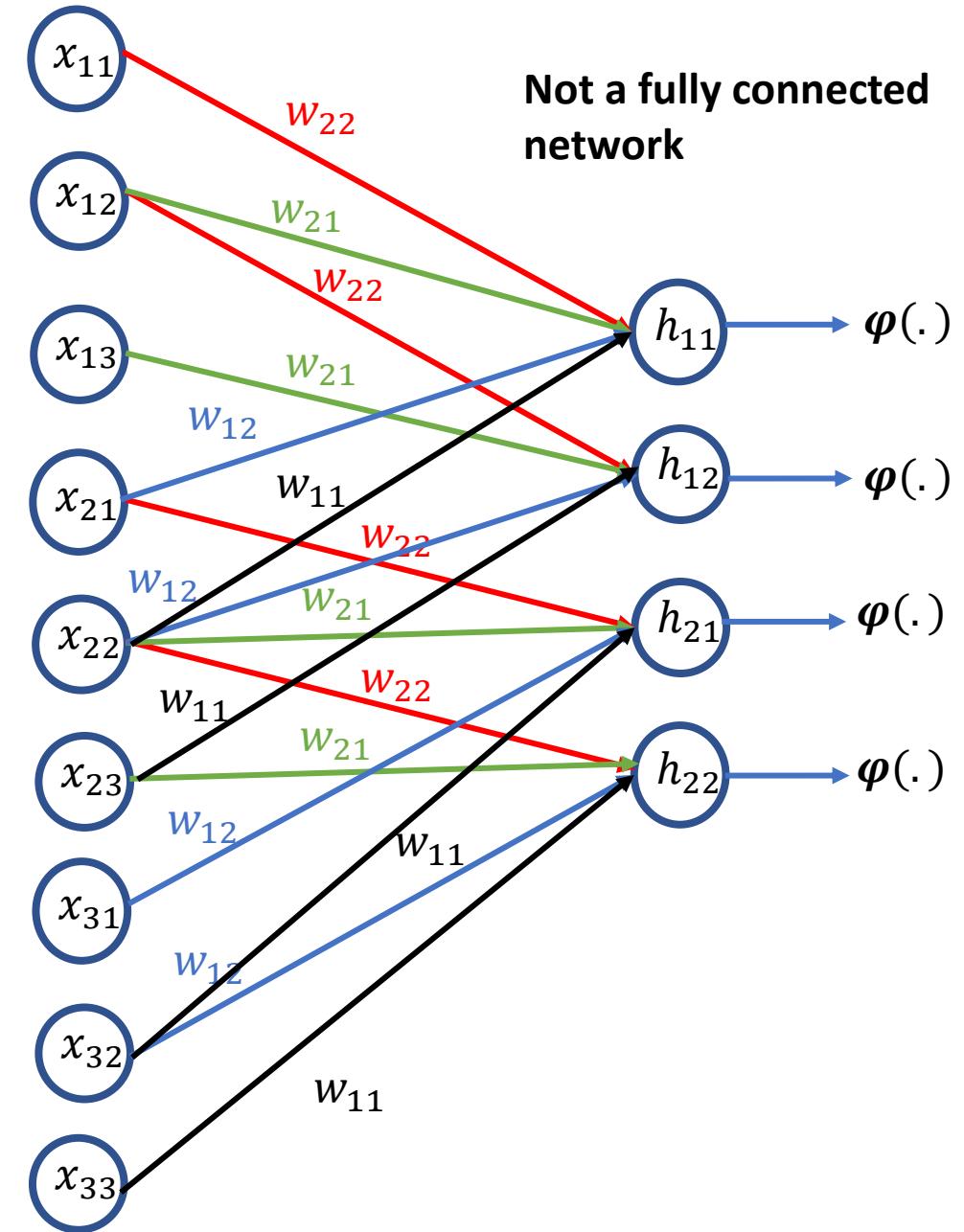
x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

$$h_{11} = x_{11}w_{22} + x_{12}w_{21} + x_{21}w_{12} + x_{22}w_{11}$$

$$h_{12} = x_{12}w_{22} + x_{13}w_{21} + x_{22}w_{12} + x_{23}w_{11}$$

$$h_{21} = x_{21}w_{22} + x_{22}w_{21} + x_{31}w_{12} + x_{32}w_{11}$$

$$h_{22} = x_{22}w_{22} + x_{23}w_{21} + x_{32}w_{12} + x_{33}w_{11}$$



Forward pass

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

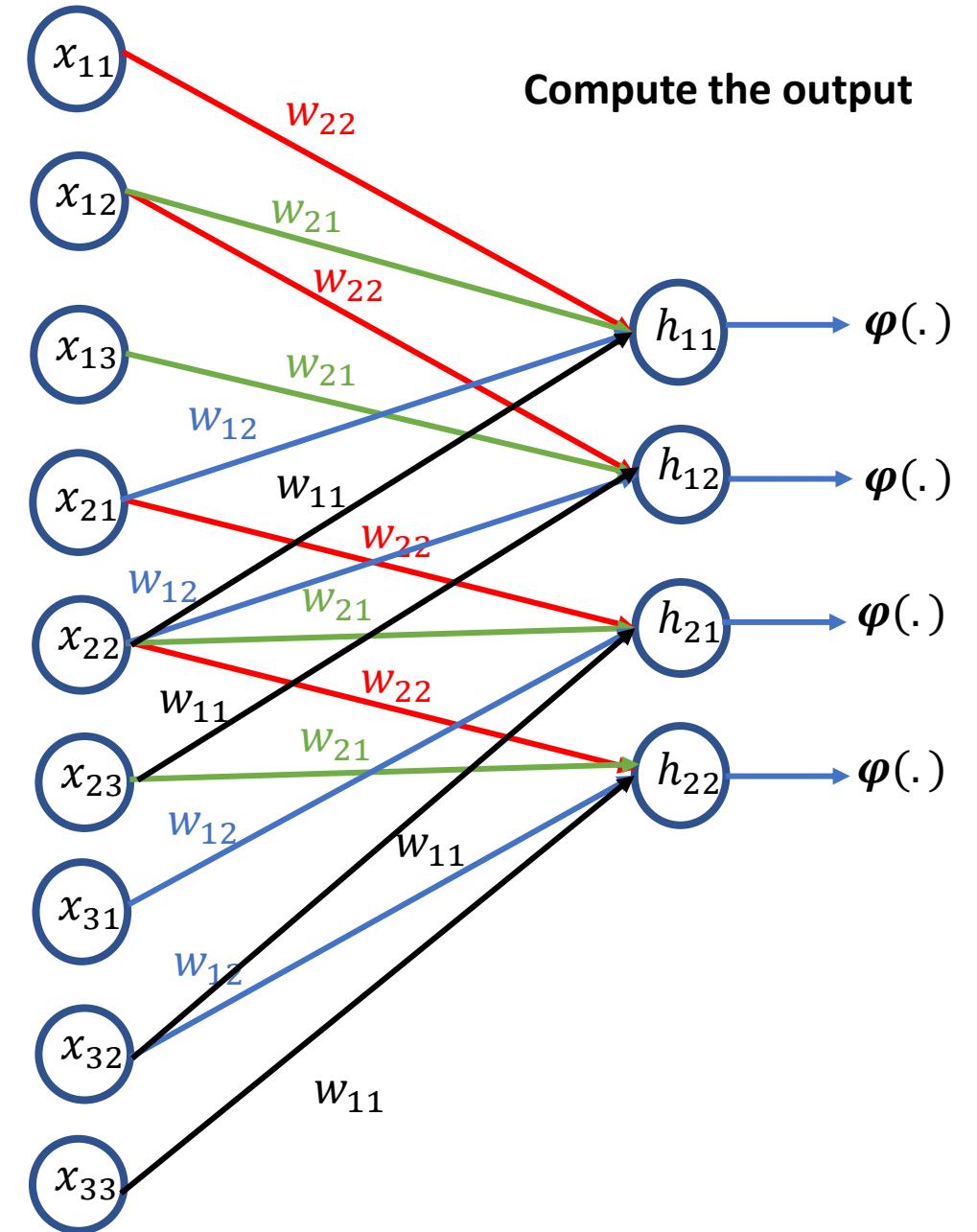
x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

$$h_{11} = x_{11}w_{22} + x_{12}w_{21} + x_{21}w_{12} + x_{22}w_{11}$$

$$h_{12} = x_{12}w_{22} + x_{13}w_{21} + x_{22}w_{12} + x_{23}w_{11}$$

$$h_{21} = x_{21}w_{22} + x_{22}w_{21} + x_{31}w_{12} + x_{32}w_{11}$$

$$h_{22} = x_{22}w_{22} + x_{23}w_{21} + x_{32}w_{12} + x_{33}w_{11}$$



Pooling

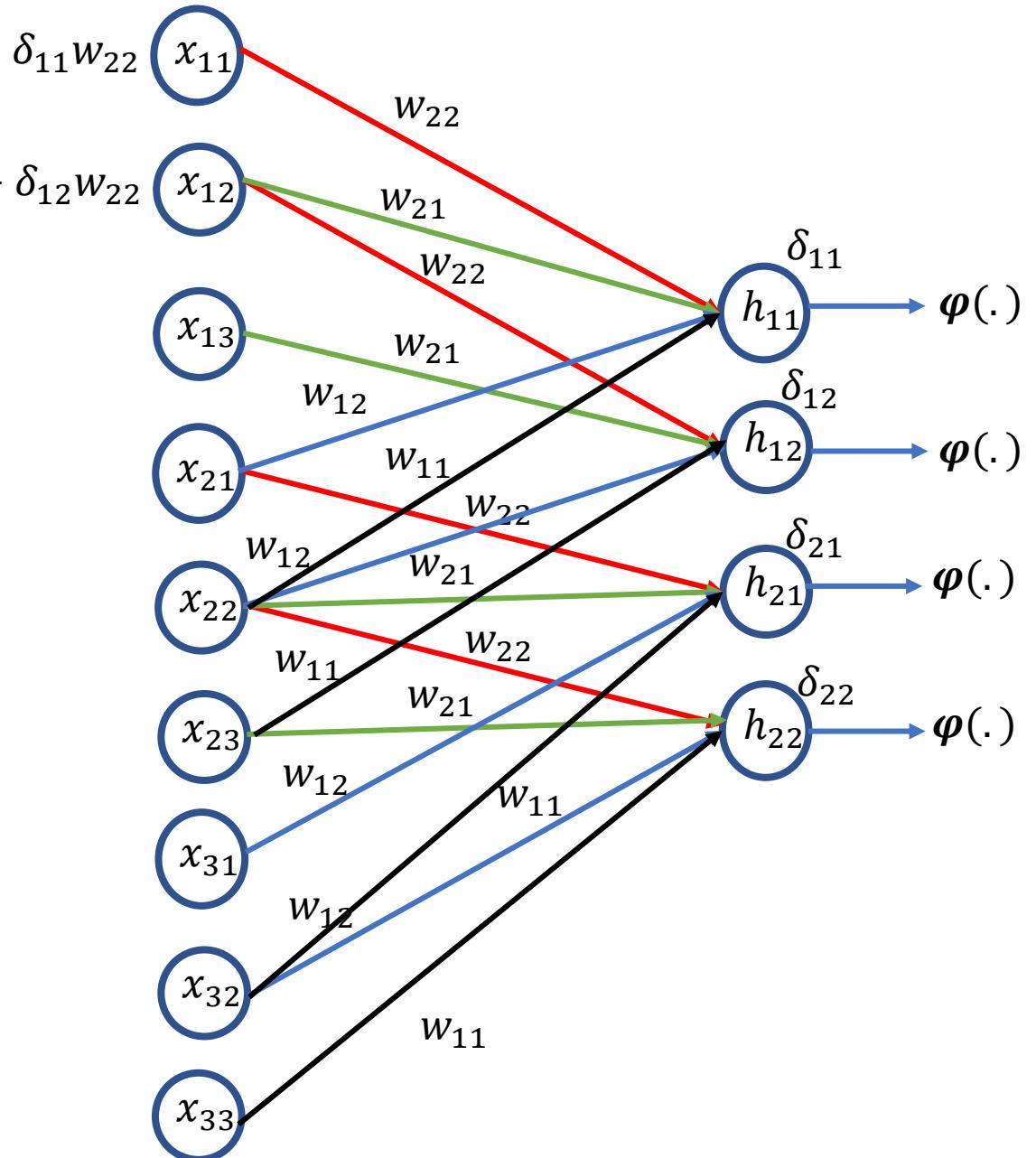
Backward pass

$$\begin{matrix} w_{22} & w_{21} \\ \hline w_{12} & w_{11} \end{matrix}$$



$$\begin{matrix} \delta_{11} & \delta_{12} \\ \hline \delta_{21} & \delta_{22} \end{matrix}$$

$$\delta_{11}w_{21} + \delta_{12}w_{22}$$



Backward pass

w_{22}	w_{21}
w_{12}	w_{11}



δ_{11}	δ_{12}
δ_{21}	δ_{22}

$Rot(180)$

w_{11}	w_{12}
w_{21}	w_{22}

$\delta_{11}w_{22}$	$\delta_{11}w_{21} + \delta_{12}w_{22}$	$\delta_{12}w_{21}$
$\delta_{11}w_{12} + \delta_{21}w_{22}$	$\delta_{11}w_{11} + \delta_{12}w_{12} + \delta_{21}w_{21} + \delta_{22}w_{22}$	$\delta_{12}w_{21} + \delta_{12}w_{22}$
$\delta_{21}w_{12}$	$\delta_{21}w_{11} + \delta_{22}w_{12}$	$\delta_{22}w_{11}$

w_{11}	w_{12}
δ_{11}	δ_{12}
δ_{21}	δ_{22}

w_{11}	w_{12}
δ_{11}	δ_{12}
δ_{21}	δ_{22}

w_{11}	w_{12}
w_{21}	δ_{11}
δ_{21}	δ_{22}

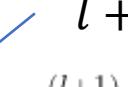
Local gradients

- In the MLP, the local gradients of neuron j in the l^{th} layer is given by $\delta_j^{(l)} = \frac{\partial E}{\partial v_j^{(l)}}$
 - Where $v_j^{(l)} = \sum_k w_{jk}^{(l)} \phi(v_k^{(l-1)}) + b_j^{(l)}$
 - This can be written in a dot product form
-
- In CNN, the dot product is replaced by a convolution operator and we define the local gradient as $\delta_j^{(l)} = \frac{\partial E}{\partial v_j^{(l)}}$
 - where $v_{x,y}^{(l)} = \sum_a \sum_b w_{a,b}^{(l)} \phi(v_{x-a,y-b}^{(l-1)}) + b_{x,y}^{(l)}$

Local gradients cont.

$$\delta_{x,y}^{(l)} = \sum_{x'} \sum_{y'} \frac{\partial E}{\partial v_{x',y'}^{(l+1)}} \frac{\partial v_{x',y'}^{(l+1)}}{\partial v_{x,y}^{(l)}} = \sum_{x'} \sum_{y'} \delta_{x',y'}^{(l+1)} \frac{\partial (\sum_a \sum_b w_{a,b}^{(l+1)} \phi(v_{x'-a,y'-b}^{(l)}) + b_{x',y'}^{(l)})}{\partial v_{x,y}^{(l)}}$$

Let $x' - a = x$ and $y' - b = y$

$$\delta_{x,y}^{(l)} = \sum_{x'} \sum_{y'} \delta_{x',y'}^{(l+1)} w_{x'-x,y'-y}^{(l+1)} \phi(v_{x,y}^{(l)})' = \delta^{(l)} \star w_{-x,-y}^{(l+1)} \phi(v_{x,y}^{(l)})'$$


Where $w_{-x,-y}^{(l+1)} = Rot_{180}(w_{x,y}^{(l+1)})$

Gradient computation

$$\frac{\partial E}{\partial w_{a,b}^{(l)}} = \sum_x \sum_y \frac{\partial E}{\partial v_{x,y}^{(l)}} \frac{\partial v_{x,y}^{(l)}}{\partial w_{a,b}^{(l)}} = \sum_x \sum_y \delta_{x,y}^{(l)} \frac{\partial (\sum_{a'} \sum_{b'} w_{a',b'}^{(l)} \phi(v_{x-a',y-b'}^{(l-1)}) + b_{x,y}^{(l)})}{\partial w_{a,b}^{(l)}}$$

When $a = a'$ and $b = b'$

$$\frac{\partial E}{\partial w_{a,b}^{(l)}} = \sum_x \sum_y \delta_{x,y}^{(l)} \phi(v_{x-a,y-b}^{(l-1)}) = \delta^{(l)} \star \phi(v_{-a,-b}^{(l-1)})$$

Where $\phi(v_{-a,-b}^{(l-1)}) = Rot_{180}(\phi(v_{a,b}^{(l-1)}))$

Summary

- Compute the error E at the output
- For every input compute $v_{x,y}^{(l)} = \sum_a \sum_b w_{a,b}^{(l)} \phi(v_{x-a,y-b}^{(l-1)}) + b_{x,y}^{(l)}$
- During back propagation, we compute the local gradient $\delta_{x,y}^{(l)}$ as

$$\delta_{x,y}^{(l)} = \sum_{x'} \sum_{y'} \delta_{x',y'}^{(l+1)} w_{x'-xy'-y}^{(l+1)} \phi(v_{x,y}^{(l)})' = \delta^{(l)} \star w_{-x,-y}^{(l+1)} \phi(v_{x,y}^{(l)})'$$


- Compute $\frac{\partial E}{\partial w_{a,b}^{(l)}} = \sum_x \sum_y \delta_{x,y}^{(l)} \phi(v_{x-a,y-b}^{(l-1)}) = \delta^{(l)} \star \phi(v_{-a,-b}^{(l-1)})$